

Kasper is a FULLY AUTONOMOUS Mini Unmanned Ground Rover. It is capable of carrying a 500 Gram payload. The payload is a Day or Night Camera mounted on a pan/tilt gimbal. The Rover is electrically powered with a very low dB level. The Rover is fully autonomous right from start to end. The Rover is made of ABS Plastic and Glass Fiber Composites

#### **Physical Specifications:**

Length : 350mm Height : 150 mm Weight : 1500 gms Payload : 500 gms

Power : 500 Watt BLDC Motors @ 7.2 Volt

Drive Terrain : Full Time 4WD

Power Battery: Lithium-Poly 7.2 Volt, 3200mAh

#### Characteristics

Range : 0.5 Km\*

Endurance : 20 Mins + 2 Mins reserve for failsafe Accuracy : Within 3 meters of programmed waypoint

Cruise Speed : 30 Km/Hr Max Speed : 50 Km/Hr Altitude Ceiling : 5000 Meters \*Total Distance Travelled: 5.0Km

# Capabilities

- Fully Autonomous from Start to Return
- · Can be programmed for 300 Waypoints
- Can Hold around the subject at any waypoint
- Has Manual over ride at any stage
- Can be 'Directed' to specific location during mission by clicking over map
- Can activate/deactivate any payload from the GCS
- Auto payload activation on reaching the waypoint
- Failsafe built in. Will 'RTH' if link is lost on the same return path

### Standard Pacakge

- · Rover Vehicle 1 Nos
- GCS consisting of windows based laptop and Video Monitor
- Patch Video Antenna
- Clover Leaf Video Antenna
- Auto Antenna Tracker (optional)
- Yagi Antenna for Data Link
- Microprocessor based battery Charger
- · Radio Control Transmitter
- Mini Tool Kit
- · Aluminum Packing Case
- Video Packing Box

### Datalink

Output Power : 100mW (Configurable)

Modulation Type: FHSS

Freq Band : 900 Mhz (885-915 Mhz)
Baud Rate : 19,200kbps (Selectable)
Range : 0.5 Km (with Yagi Antenna)





### Autopilot

- Based on ARM Cortex M4 32 bit Processor @168 Mhz, running at 252 MIPS, on NuttX Real Time Operating System
- ST Micro L3GD20, 3-Axis Gyro
- MPU6000, Invensense 3-Axis Gyro +Accelerometer
- High Accuracy, uBlox GPS with positioning from GPSS, GLONSS, Galelio, Biedu
- HMC5883L 3-Axis Dual Magnetometer (Dual)
- MS5611 High Resolution Barometer
- Onboard Micro SD card for Data Logging

# Video Link

Type : Digital Secured Video (Wi-Fi based)

Rf Power : 270mW

Frequency : 2.4 Ghz, 40 Channels Power Consumption : 300mA @11.1 V Video Resolution : 1280x720 (HD)

Camera Mount : High Accuracy Gyro Stabilizatin on

Roll and Pitch Axis

Recording : Onboard recording on 32 GB SD card

in \*.avi format

#### Radio Control Link

Encoding : PPM
Modulation : FHSS
Freq Band : 2.4 Ghz
Max Rf Output : 100mW Max

Channels : 8

Manual Control Range : 0.5 Km (only if Line of Sight)
Display : Back-Lit LCD panel on Tx
Battery : Li-Poly 11.1V, 2650 mAh (12 Hrs

continuous operation)



#### Onboard Video Recorder

32GB onboard micro SD card recorder. H.264 compression.\*.aviformat

#### Camera Gimbal

Pan/Tilt controllable from GCS

## Payload Options

- Option 1: Color video/still HD camera with onboard HD video recording on 32 GB memory at 1280x720 pixels and AV out of 640x480 pixels. Can be programmed for still images with preset time interval. Max Video HD resolution of 2700 x 2000 pixels
- Option 2: Thermal Camera (uncooled) 640x480 Res and 40 Deg FOV (selectable) with athermal lens







# Kasper Autonomous **4WD** Rover



# Our other products...



Baaz Mini UAV



Guardian Civilian UAV







Curiosity Plus Quadcopter UAV



Kisan Crop Duster



Solo Multicopter



Surveyor-I



Pushpak Hexacopter



Curiosity Quadcopter UAV

OM UAV Systems
60-UA, Jawahar Nagar, Delhi 110 007, India
sales@omuavsystems.com, www.omuavsystems.com, Contact: Ravindra Singh, Mob.: +91 9810442574